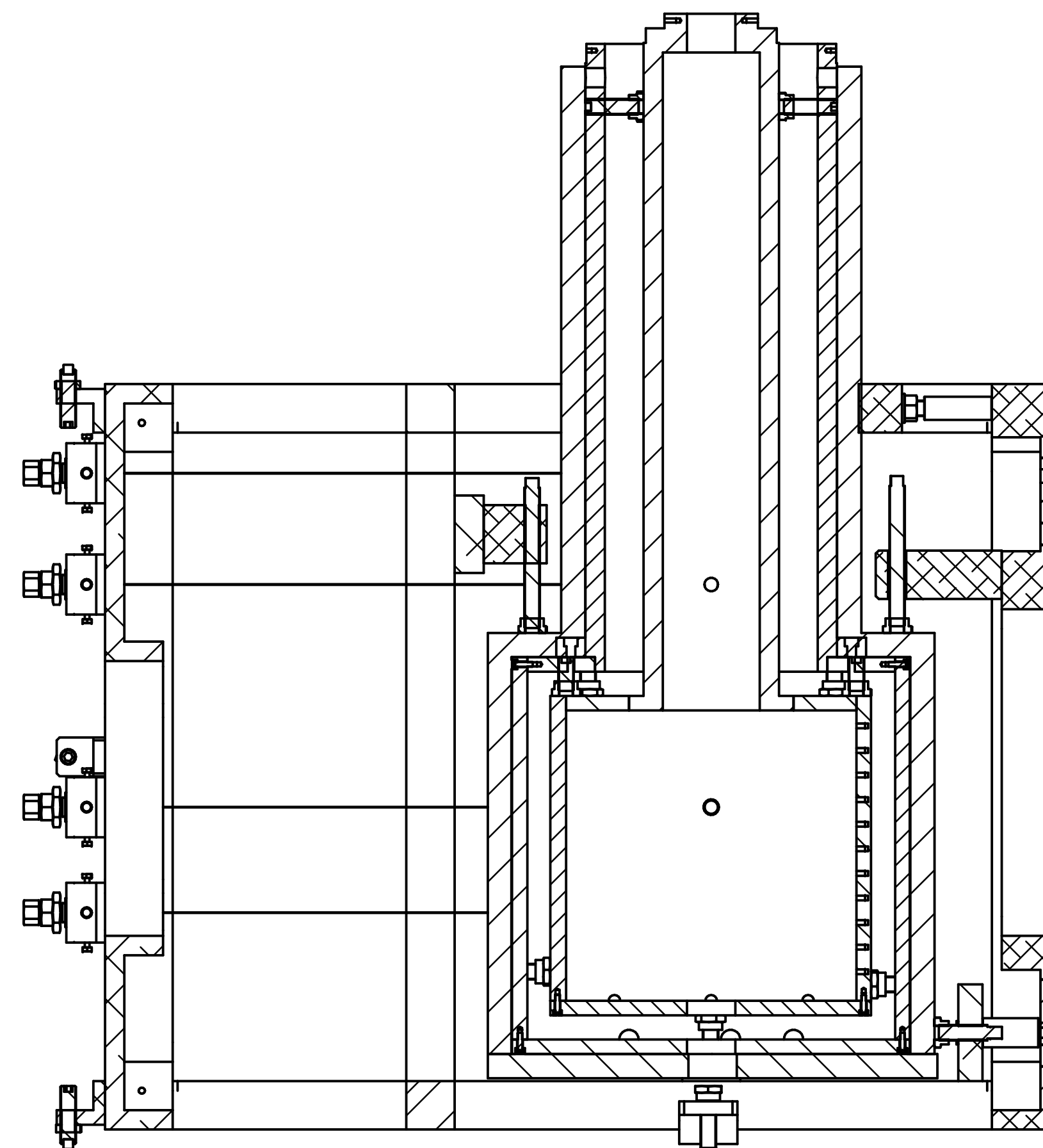


REVISION HISTORY			
REV	DESCRIPTION	DATE	APPROVED



The top view shows the robot platform with its components and the path of the red laser line. The components are arranged as follows:

- Top View Components:**
 - Top:** A row of 12 sensors (6 on the left, 6 on the right) and a central sensor.
 - Left Side:** A vertical row of 4 sensors (2 on the left, 2 on the right) and a central sensor.
 - Right Side:** A vertical row of 4 sensors (2 on the left, 2 on the right) and a central sensor.
 - Bottom:** A row of 12 sensors (6 on the left, 6 on the right) and a central sensor.
 - Center:** A large octagonal area.
- Red Laser Line Path:** A dashed red line runs vertically through the center of the platform, passing through the central sensors on the top, left, right, and bottom sides, and through the central octagonal area.
- Red Laser Line Labels:** The label "B" is placed at the top and bottom of the red laser line, with arrows pointing to the line.

	NAME	DATE	Solid Edge					
DRAWN	fomar	05/2/21				TITLE Assieme Telaio _Camera Sperim_ Schermo_Blocc_Sospens.		
CHECKED								
ENG APPR								
MGR APPR			SIZE	DWG NO	REV			
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MILLIMETERS ANGLES = °X* 2 PL = XXXX 3 PL = XXXXX			A1	TSTC_T_104	0			
			FILE NAME: TSTC_T_104 Assieme Telaio Supporto con Camera Sperim.					
			SCALE:	WEIGHT:	SHEET 2 OF 2			