

Time Series Analysis

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Class 4

MA(1): Moving Average of first order

- The value of the random variable X_t (at time t) depends on the combination of two **shocks** (uncorrelated variables with zero mean and constant variance), the shock at time t and that related to a previous time $t - 1$ with a coefficient θ :

$$X_t = \theta\epsilon_{t-1} + \epsilon_t$$

$$\epsilon_t \sim WN(0, \sigma^2)$$

$$(X_t = \mu + \theta\epsilon_{t-1} + \epsilon_t)$$

- Such process is considered as a result of the sum of past and present time random shocks.
- The *MA* models can be used to study phenomena with high irregularities characterized by a serial autocorrelation that vanishes after few lags.

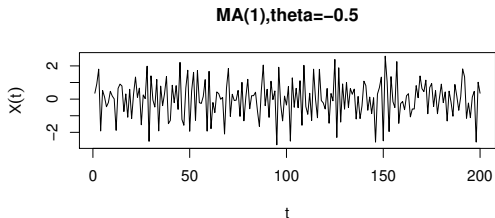
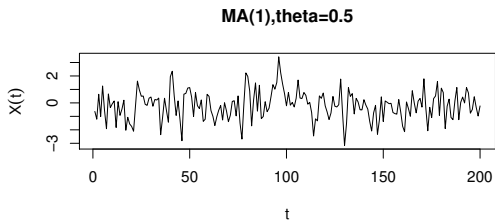


Figure: Path of two time series MA(1), zero mean where $\theta = 0.5$ and $\theta = -0.5$ and $\epsilon_t \sim WN(0, 1)$..

- The MA(1) process is **always stationary**:

$$\mathbb{E}(X_t) = \mathbb{E}(\theta\epsilon_{t-1} + \epsilon_t) = \theta\mathbb{E}(\epsilon_{t-1}) + \mathbb{E}(\epsilon_t) = 0$$

$$\text{Var}(X_t) = \gamma(0) = \mathbb{E}(\theta\epsilon_{t-1} + \epsilon_t)^2 =$$

$$= \mathbb{E}(\theta^2\epsilon_{t-1}^2 + \epsilon_t^2 + 2\theta\epsilon_t\epsilon_{t-1}) =$$

$$= \theta^2\sigma^2 + \sigma^2 + 0 = (1 + \theta^2)\sigma^2$$

$$(\mathbb{E}(X_t) = \mathbb{E}(\mu + \theta\epsilon_{t-1} + \epsilon_t) = \mu + \theta\mathbb{E}(\epsilon_{t-1}) + \mathbb{E}(\epsilon_t) = \mu)$$

- The ACF a lag 1 is:

$$\begin{aligned}\gamma(1) &= \mathbb{E}(X_t X_{t-1}) = \mathbb{E}[(\theta \epsilon_{t-1} + \epsilon_t)(\theta \epsilon_{t-2} + \epsilon_{t-1})] = \\ &\theta^2 \mathbb{E}(\epsilon_{t-1} \epsilon_{t-2}) + \theta \mathbb{E}(\epsilon_{t-1}^2) + \theta \mathbb{E}(\epsilon_t \epsilon_{t-2}) + \mathbb{E}(\epsilon_t \epsilon_{t-1}) = \\ &= \theta^2 \times 0 + \theta \times \sigma^2 + \theta \times 0 + 0 = \theta \sigma^2 \\ \gamma(h) &= 0 \quad \text{for } h \geq 2.\end{aligned}$$

- Autocovariances vanish since the ϵ_t are uncorrelated.
- The memory of a process $\{X_t\}$ of the kind $MA(1)$ lasts for **only one period (lag)**.
- **Stationarity**: there is no dependence of time.

- Compute the autocorrelation (see how the ACF looks like):

$$\rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{\theta\sigma^2}{(1+\theta^2)\sigma^2} = \frac{\theta}{1+\theta^2} \Rightarrow -0.5 \leq \rho(1) \leq 0.5$$

$$\rho(h) = 0 \quad \forall h \geq 2.$$

- The maximum of $\rho(1)$ is obtained when $\theta = 1$ and the minimum when $\theta = -1$. In those values the ACF is, respectively, 0.5 e -0.5 .
- The theoretical ACF of an MA(1) can be plotted as a function of h for different values of θ .

Stationary property

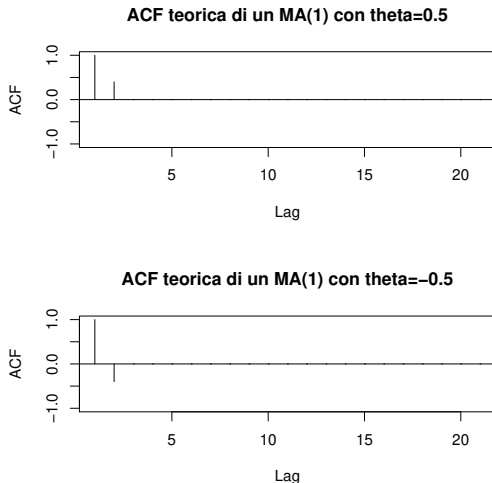
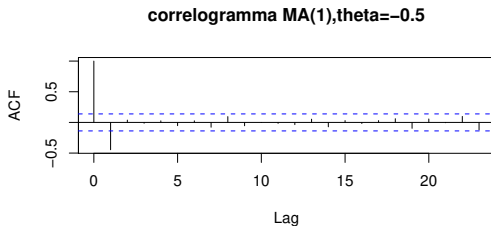
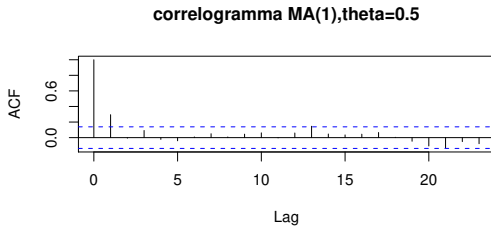


Figure: Theoretical ACF of two MA(1) processes.

- For simulated series correlograms are the **analogue of ACF**.



- PACF is given by:

$$\phi_{hh} = \frac{-(-\theta)^h}{1 + \theta^2 + \dots + \theta^{2h}},$$

that is,

$$\phi_{11} = \frac{\theta}{1 + \theta^2}, \quad \phi_{22} = \frac{-(-\theta)^2}{1 + \theta^2 + \theta^4}, \dots$$

- In contrast with the ACF that decays at the first lag, PACF of an MA(1) decays with alternating signs if $\theta > 1$ and vanishes at an exponential rate after the first lag if $\theta < 1$.
- PACF goes to zero slowly after the first lag.

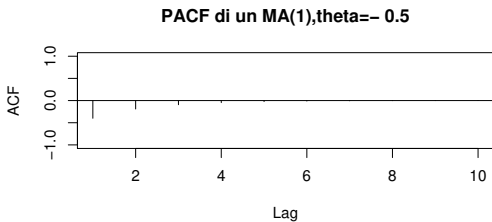
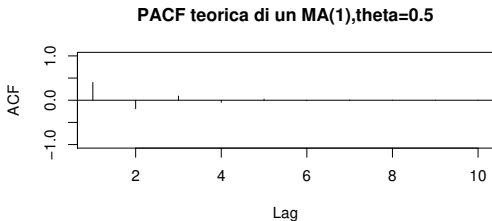
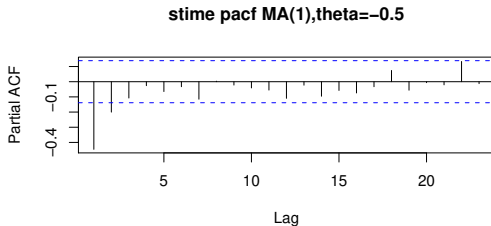
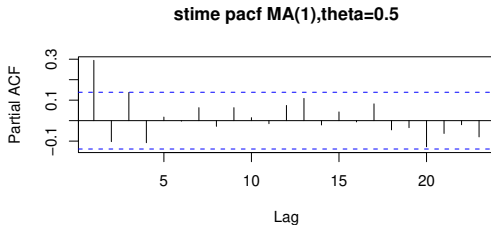


Figure: Theoretical PACF of two MA(1) processes.

- For the simulated series estimated PACF are:



The identification issue: Invertibility

- Consider the following $MA(1)$ processes:

$$X_t = \theta\epsilon_{t-1} + \epsilon_t$$

$$Y_t = \theta^*\epsilon_{t-1} + \epsilon_t,$$

where

$$\theta^* = \frac{1}{\theta}.$$

Then,

$$\rho_X(1) = \frac{\theta}{1 + \theta^2} \quad \rho_Y(1) = \frac{\theta^*}{1 + \theta^{*2}}$$

- The ACF is the same:

$$\rho_Y(1) = \frac{1/\theta}{1 + 1/\theta^2} = \frac{\theta}{1 + \theta^2} = \rho_X(1)$$

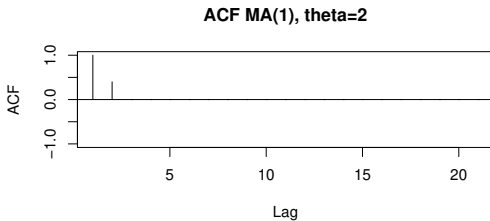
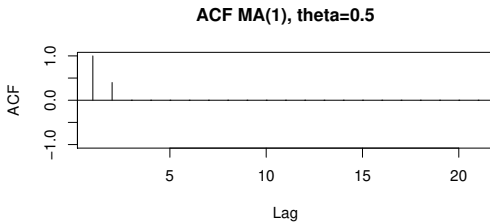


Figure: MA(0.5) and MA(2.0) show same ACF.

- It has been shown that two $MA(1)$ processes (of the same order) with parameters one the reciprocal of the other, have same autocorrelations.
- Therefore, it is not possible to **identify** the process underlying the observed time series only by looking at the ACF.
- This issue concerns the entire class of MA processes.
- In order to avoid such problem we consider **invertible** MA , that is processes that satisfy $|\theta| < 1$.
- It can be shown that if $|\theta| < 1$, the process $X_t = \theta\epsilon_{t-1} + \epsilon_t$ has a representation of the kind: $X_t = h(X_{t-1}, X_{t-2}, \dots) + \epsilon_t^*$.
- **The Invertibility condition is independent of stationarity condition.**

- The lag operator allows to write the MA(1) as:

$$X_t = \theta\epsilon_{t-1} + \epsilon_t = (1 + \theta B)\epsilon_t = \Theta(B)\epsilon_t$$

- It can be shown that such process is **invertible** if the characteristic equation $\Theta(B) = 0$ admits a (unique) root in B , $|B| > 1$, i.e.,

$$|B| > 1 \Leftrightarrow |\theta^{-1}| > 1 \Leftrightarrow |\theta| < 1.$$

- If $|\theta| < 1$ then

$$(1 + \theta B)^{-1} = (1 - (-\theta B))^{-1} = \sum_{j=0}^{\infty} (-\theta)^j B^j.$$

Then,

$$\epsilon_t = (1 - \theta B + \theta^2 B^2 - \theta^3 B^3 + \dots) X_t$$

so

$$X_t = \theta X_{t-1} - \theta^2 X_{t-2} + \theta^3 X_{t-3} + \dots + \epsilon_t.$$

Impulse function

- The **impulse function** measures the effect of a unit variation of the random variable ϵ on the X through time. Specifically, this function assesses the persistence of the random shock.
- For an $MA(1)$ process it is given by:

$$\frac{\partial X_t}{\partial \epsilon_t} = 1,$$

$$\frac{\partial X_{t+1}}{\partial \epsilon_t} = \theta,$$

$$\frac{\partial X_{t+j}}{\partial \epsilon_t} = 0 \quad \forall j > 1.$$

- The shock has effect on one period ahead only and its intensity depends on the value of the parameter θ .

- The $MA(1)$ model is very parsimonious because it contains only one unknown parameter but it is not flexible enough as the information at time t become useless starting at time $t + 2$.
- Moreover, ACF only lasts one lag and the maximum value it reaches is $|0.5|$.
- We will study how to make this model more flexible by increasing the memory of the process.