

## **Syllabus of Linear Algebra**

1. Linear combination of vectors: geometric and coordinate representation
2. Scalar and cross product
3. Linear transformations of vectors and matrices
4. Transpose of a matrix and symmetric matrices
5. Determinant and inverse matrices
6. Eigenvalues and eigenvectors of matrices
7. Orthogonal matrices
8. Representations of rotations of a rigid body: Euler angles and quaternions

## **Syllabus of Dynamical Systems**

1. Derivatives of a function  $f(x)$
2. Geometrical interpretation of  $df/dx$
3. Differential equations and some examples with analytic solutions
4. Systems of differential equations
5. Linear differential equations: homogeneous and forced
6. Complex numbers
7. Laplace transform
8. Solution of differential equations by Laplace transform
9. The transfer function and transfer matrix of linear systems

## **Matlab Programming**

Matlab code will be applied to the subjects covered by Linear Systems and Dynamical Systems, with examples and exercises.