



ABOUT ME

Ph.D. student in Aeronautics and Space Engineering at "La Sapienza" University of Rome.

WORK EXPERIENCE

10/2024 – CURRENT Rome, Italy

Junior Research Fellow Department of Mechanical and Aerospace Engineering , "La Sapienza" University of Rome

Winner of the Junior Research Fellowship entitled:

[ITA] "Analisi di dati ottici mediante tecniche di Computer Vision per la missione Europa Clipper"

[ENG] "Optical Data Analysis Using Computer Vision Techniques for the Europa Clipper Mission"

05/12/2023 – 05/10/2024 Rome, Italy

Junior Research Fellow Department of Mechanical and Aerospace Engineering , "La Sapienza" University of Rome

Winner of the Junior Research Fellowship entitled:

[ITA] "Attività di verifica e validazione del software di generazione ed elaborazione dei dati altimetrici"

[ENG] "Software Testing and Validation for Altimetric Data Generation and Processing"

01/07/2023 – 31/10/2023 Rome, Italy

Junior Research Fellow Department of Mechanical and Aerospace Engineering , "La Sapienza" University of Rome

Winner of the Junior Research Fellowship entitled:

[ITA] " Analisi combinata di dati altimetrici e ottici per la determinazione orbitale della sonda Europa Clipper"

[ENG] "Combined Analysis of Altimetric and Optical Data for Orbital Determination of the Europa Clipper Probe"

EDUCATION AND TRAINING

2023 – CURRENT Rome, Italy

Ph.D. in Aeronautics and Space Engineering University of Rome "La Sapienza"

Website <https://www.uniroma1.it/it/pagina-strutturale/home> |

Field of study Robotics Space Systems | Level in EQF EQF level 8

2020 – 2023

MSc in Space and Astronautical Engineering University of Rome "La Sapienza"

After the BSc in Aerospace Engineering I have enrolled in MSc Space and Astronautical Engineering choosing Mission curriculum. Currently I have already followed and certified the following courses:

1. Gasdynamics
2. SpaceFlight Mechanics
3. Control Systems
4. Space Structures
5. Space Missions and Systems
6. Interplanetary Trajectories
7. Fluidodynamics Astrophysics and Geophysics
8. Advanced Spacecraft Dynamics

9. Electronics
10. Electronics of Space Systems
11. Space Guidance and Navigation
12. Space Propulsion
13. Robotics Space Systems

ABSTRACT:

The thesis focuses on designing and testing a 2D Online Visual-SLAM (VSLAM) navigation system using the Extended Kalman Filter and maximum likelihood data association without prior environmental knowledge. It aims to enable real-time localization and mapping for autonomous planetary rovers. The system is implemented on ROS2 and tested through simulations in GAZEBO, comparing its performance to dead reckoning. This research addresses the challenges of autonomous navigation in uncharted environments.

Website <https://www.uniroma1.it/it/pagina-strutturale/home> | **Field of study** Robotics Space Systems |

Final grade 107/110 | **Level in EQF** EQF level 7 | **National classification** Laurea Magistrale | **Type of credits** ECTS |

Number of credits 120 | **Thesis** Visual SLAM for Planetary Rovers

2015 – 2020

BSc in Aerospace Engineering University of Rome "La Sapienza"

During in the BA in addition of compulsory courses I focused on specific topics regarding space mission, space environment, aerospace construction technology and structural calculation laboratory.

Certificated Exams for Aerospace Engineering :

- Aerodynamics
- Space Environment
- Space Systems
- Numerical Methods
- Aerospace Structures
- Aeronautic and Space Propulsion
- Atmospheric and Spaceflight Mechanics
- Aerospace Materials Technology
- Telecommunication Systems

I acquired skills:

Structural analysis using Nastran and Patran Software

Matlab for simulations, integration of differential equations system, non linear and linear equations.

Thesis Work:

Working on BA Thesis I analyzed the effect of the atmospheric drag on a cubesat in Venusian orbit and verify if such satellite standard is a good choice for mission high risk high reward. The analysis required a big effort to integrate numerically the Gauss Equations using MATLAB. The analysis of Venus atmosphere was performed by using Venus Gram 2005, a Fortran based software developed by MSFC (Marshall Space Flight Center, Nasa) from which I extracted the atmospheric data to implement a simpler model included in the code for the integration.

Website <https://www.uniroma1.it/it/pagina-strutturale/home> | **Field of study** Aerospace Engineering |

Final grade 104/110 | **Level in EQF** EQF level 6 | **National classification** Laurea Triennale | **Type of credits** ECTS |

Number of credits 180 | **Thesis** The effect of atmospheric drag on a cubesat in a venusian orbit

09/2013 – 05/2014 Coorparoo (Brisbane), Australia

Exchange Student in Australia Coorparoo Secondary College

Address Stanley St E & Cavendish Road, QLD 4151, Coorparoo (Brisbane), Australia | **Website** <https://coorparoosecondarycollege.eq.edu.au/>

09/2009 – 07/2015 Ciampino (RM), Italy

Scientific High School Diploma Liceo Scientifico Statale " Vito Volterra"

Address Via dell'Acqua Acetosa 8A, 00043, Ciampino (RM), Italy | **Website** <http://www.liceovolterra.edu.it/> |

Final grade 98/100 | **Level in EQF** EQF level 4 | **National classification** Diploma Liceale

LANGUAGE SKILLS

MOTHER TONGUE(S): Italian

Other language(s):

English

Listening C1

Spoken production B2

Reading C1

Spoken interaction B2

Writing B2

Levels: A1 and A2: Basic user; B1 and B2: Independent user; C1 and C2: Proficient user

DIGITAL SKILLS

AnacondaPython | Programming(Matlab, Python) | Robotics Toolbox MATLAB | Robotics toolbox python | Robotic
Operative System (ROS) | Linux: Intermediate user | Microsoft/Microsoft Office | MATLAB, Simulink, | JPL MONTE
orbit determination code | C++

NETWORKS AND MEMBERSHIPS

● **2018 – 2019** University of Rome "La Sapienza"

● **Sapienza Rocket Team**

CONFERENCES AND SEMINARS

● **08/12/2019 – 12/12/2019** San Francisco, California (USA)

● **AGU Fall Meeting 2019**

Link <https://www.agu.org/fall-meeting-2019>

PROJECTS

● **2017 – 2018**

● **Airbus Sloshing Rocket Workshop 2018 - 2019**

I participated with the Rocket Team at the Airbus Sloshing Rocket Workshop. The project proposed to the examiners consisted in a water rocket that once ended the propulsion was capable of gliding in order to travel the maximum distance possible. Inside the rocket there was a tank with inside liquid water and the aim of the project, beside reaching the maximum distance possible, was to limit the sloshing phenomenon.

MANAGEMENT AND LEADERSHIP SKILLS

● **PhD Student Representative on the Doctoral Board of the Aeronautics and Space Engineering PhD Program**

I have been elected as the PhD Student Representative on the Doctoral Board of the Aeronautics and Space Engineering PhD Program for the 2024-2027 triennium

Link https://phd.uniroma1.it/web/PHD-STUDENTS-AERONAUTICS-AND-SPACE-ENGINEERING_n13556_EN.aspx

● **Student Representative at Academic Council of Aerospace Engineering (CAD) (Second Mandate)**

I have been elected Student Representative at Academic Council of Aerospace Engineering for the biennial 2021-2023.

Member of Working Group MSAR (Master Degree in Space and Astronautical Engineering)

Member of Working Group Quality Assurance Management Commission

Member of Council of Aerospace Engineering

● **Student Representative at Academic Council of Aerospace Engineering (CAD)**

I have been elected Student Representative at Academic Council of Aerospace Engineering for the biennial 2019-2021, I am member of the BAER's Work Group and I am spokesman for the first year MSAR (Master Degree in Space and Astronautical Engineering).

Link http://www.ingaero.uniroma1.it/index.php?option=com_content&view=article&id=843&Itemid=1310&lang=it

● **Student Representative at Liceo Scientifico "Vito Volterra"**

During the school year 2014-2015 I was elected Student Representative for the School Board and Student Representative for the Class Board.

ADDITIONAL INFORMATIONS

● **Personal Data Treatment**

I hereby authorize the use of my personal data in accordance to Legislative Decree 30 June 2003, n. 196 "Code concerning the protection of personal data" and in accordance to GDPR 679/16 - "European regulation on the protection of personal data"