

## PERSONAL INFORMATION

Family name, First name: Mattioli Luca

## EDUCATION

- 2020-2024     PhD in Industrial and Management Engineering  
Department of Mechanical and aerospace engineering (DIMA), University of Rome “La Sapienza”, Rome, Italy  
PhD Supervisor: Eduardo Palermo
- 2016-2020     Master degree in mechanical engineering  
Department of Mechanical and aerospace engineering (DIMA), University of Rome “La Sapienza”, Rome, Italy
- 2010-2016     Bachelor degree in mechanical engineering  
Department of Mechanical and aerospace engineering (DIMA), University of Rome “La Sapienza”, Rome, Italy

## CURRENT POSITION

- 2024–Present     Researcher post-Doc  
Department of Computer, Automatic and Management Engineering (DIAG), University of Rome “La Sapienza”, Rome, Italy

## PREVIOUS POSITIONS

- 2018–2022     Middle school teacher  
Collegio S. Giuseppe, Istituto de Merode, Rome, Italy

## FELLOWSHIPS AND AWARDS

- 2024             Paolo Cappa Award, National Measurement Forum (September 2024, Garden Toscana Resosrt) - Best Plenary Session Presenter for the Mechanical and Thermal Measurements Group GMMT)

## TEACHING ACTIVITIES

- 2020 – present Assistant professor – Biomechanics, University of Rome “La Sapienza”, Rome, Italy

## PUBLICATIONS:

Journals:

L. Mattioli *et al.*, “Design and testing of SIDE: a wearable 4 DoF upper limb exoskeleton for haptic feedback in virtual reality”. Submitted at IEEE Transactions on Mechatronics, under review (01/2025).

L. Liguori *et al.*, “Performance of Ankle Exoskeletons on Irregular Terrains: Key Design Principles and Benchmarking Tests”. Submitted at IEEE Transactions Neural Systems and Rehabilitation Engineering, under review (01/2025).

L. Mattioli *et al.*, “Kinematic assessment of upper limb impairment in stroke survivors through IMUs during box and block test”. Submitted at IEEE Sensours Journal, under review. (12/2024).

V. Ronca *et al.*, “How Immersed Are You? State of the Art of the Neurophysiological Characterization of Embodiment in Mixed Reality for Out-of-the-Lab Applications,” *Applied Sciences*, vol. 14, no. 18, Art. no. 18, Jan. 2024, doi: 10.3390/app14188192.

Conference Proceedings:

L. Mattioli et al. "Simulated Dynamics Exoskeleton (SIDE): design and testing of the effects of a wearable upper limb exoskeleton on kinematics in industrial-like tasks", submitted at *2025 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Oct. 2025

F. Patanè et al., "Extrinsic Calibration of Motion Tracking Sensors in Wearable Exoskeletons: A Preliminary Study". Submitted at *2025 IEEE International Symposium on Medical Measurements and Applications (MeMeA)*, May. 2025

L. Mattioli et al., "Transparency evaluation of SIDE exoskeleton: a preliminary study for haptic VR training.". Submitted at *2025 IEEE International Symposium on Medical Measurements and Applications (MeMeA)*, May. 2025

L. D'Alvia, L. Mattioli, E. Palermo, and Z. Del Prete, "Development and Validation of an Algorithm for Calibrating Photoplethysmography Integrated Device," in *2024 IEEE International Symposium on Medical Measurements and Applications (MeMeA)*, Jun. 2024, pp. 1–6. doi: 10.1109/MeMeA60663.2024.10596893.

E. Colamarino et al., "Inter-limb muscle synergy similarity as marker of post-stroke impairment in Box & Block Test," *Gait & Posture*, vol. 105, pp. S16–S17, Oct. 2023, doi: 10.1016/j.gaitpost.2023.07.306.

L. Mattioli et al., "Kinematic evaluation of upper limb impairment in stroke survivors through box and block test and IMUs," in *2023 IEEE International Symposium on Medical Measurements and Applications (MeMeA)*, Jun. 2023, pp. 1–6. doi: 10.1109/MeMeA57477.2023.10171923.

J. Taborri et al., "RANK - Robotic Ankle: Design and testing on irregular terrains," in *2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Oct. 2022, pp. 9752–9757. doi: 10.1109/IROS47612.2022.9981580.

## **PATENTS**

*Patent Title:* Esoscheletro per interfaccia aptica con ambiente di realtà virtuale e/o aumentata

*Patent Number:* I0203595-MP

*Filing Date:* 10/2023

*Inventors:* Luciano di Donato, Eduardo Palermo, Marco Pirozzi, Alessandro Ferraro, Luca Mattioli, Fabrizio Patanè, Stefano Rossi, Giovanni Mariani, Juri Taborri, Ilaria Mileti, Antonio Lanzotti, Giuseppe di Gironimo